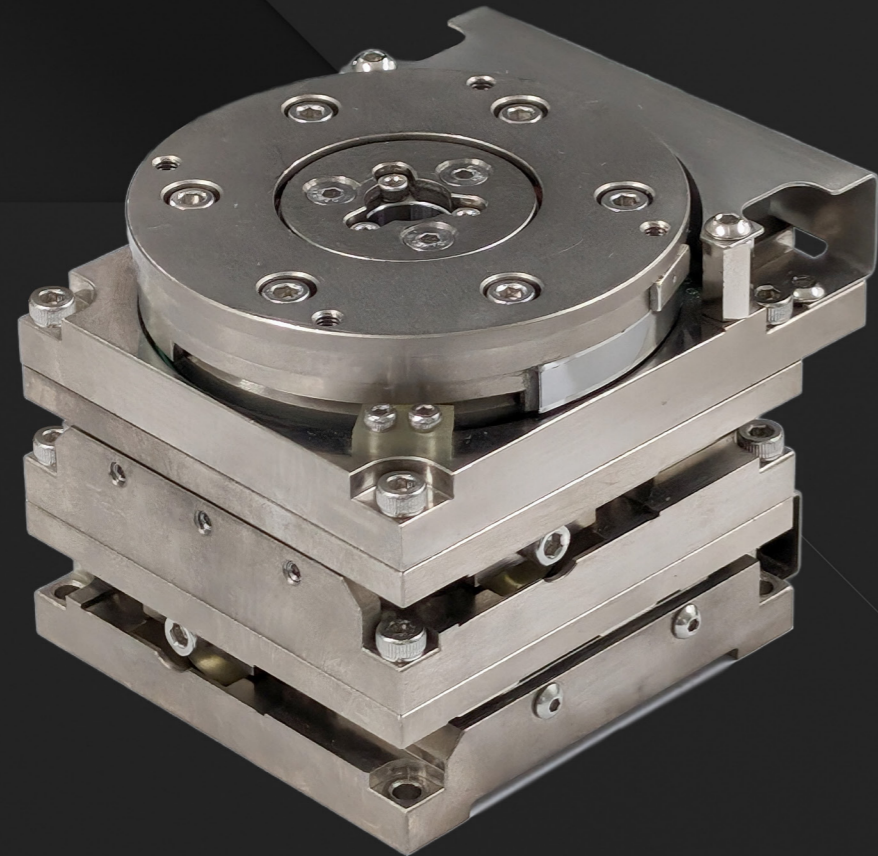




pb
SYSTEMS

DIRECT DRIVE TECHNOLOGY
Product Catalogue



PAS SERIES

ALIGNMENT STAGE

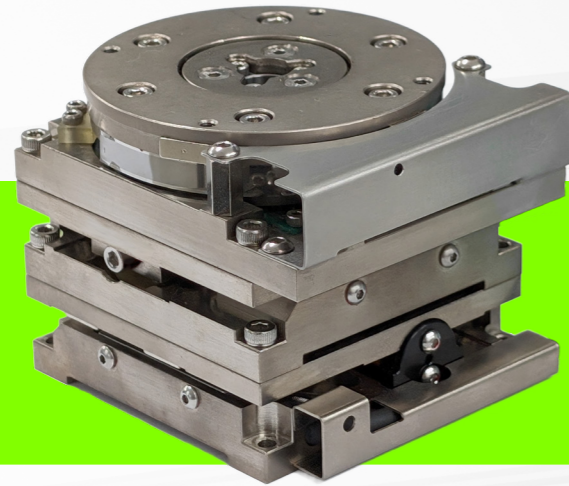
VERSION 4.1.7

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PAS SERIES

IRONLESS LINEAR MOTOR



PAS Series Alignment Stage is a low-profile, 3-axis, XYθ motion, compact, miniature stage.

Ideal for closed loop short stroke positioning applications where precision, repeatability and low speed/force ripple are of utmost importance.

PBA PAS stage is powered by PBA direct drive motors comes with built-in precision cross roller guides that provide high rigidity to complement the high acceleration capability of the PAS module which has very low electrical/mechanical time constants and zero hysteresis.

With the combination of high-resolution linear encoder, PBA PAS Stage ensures high-accuracy positioning operation without any backlash. It is most suitable for alignment processing utilizing image processing such as semiconductor and liquid crystal related manufacturing equipment, and positioning mechanism for measuring equipment and inspection instruments that require clean environments.

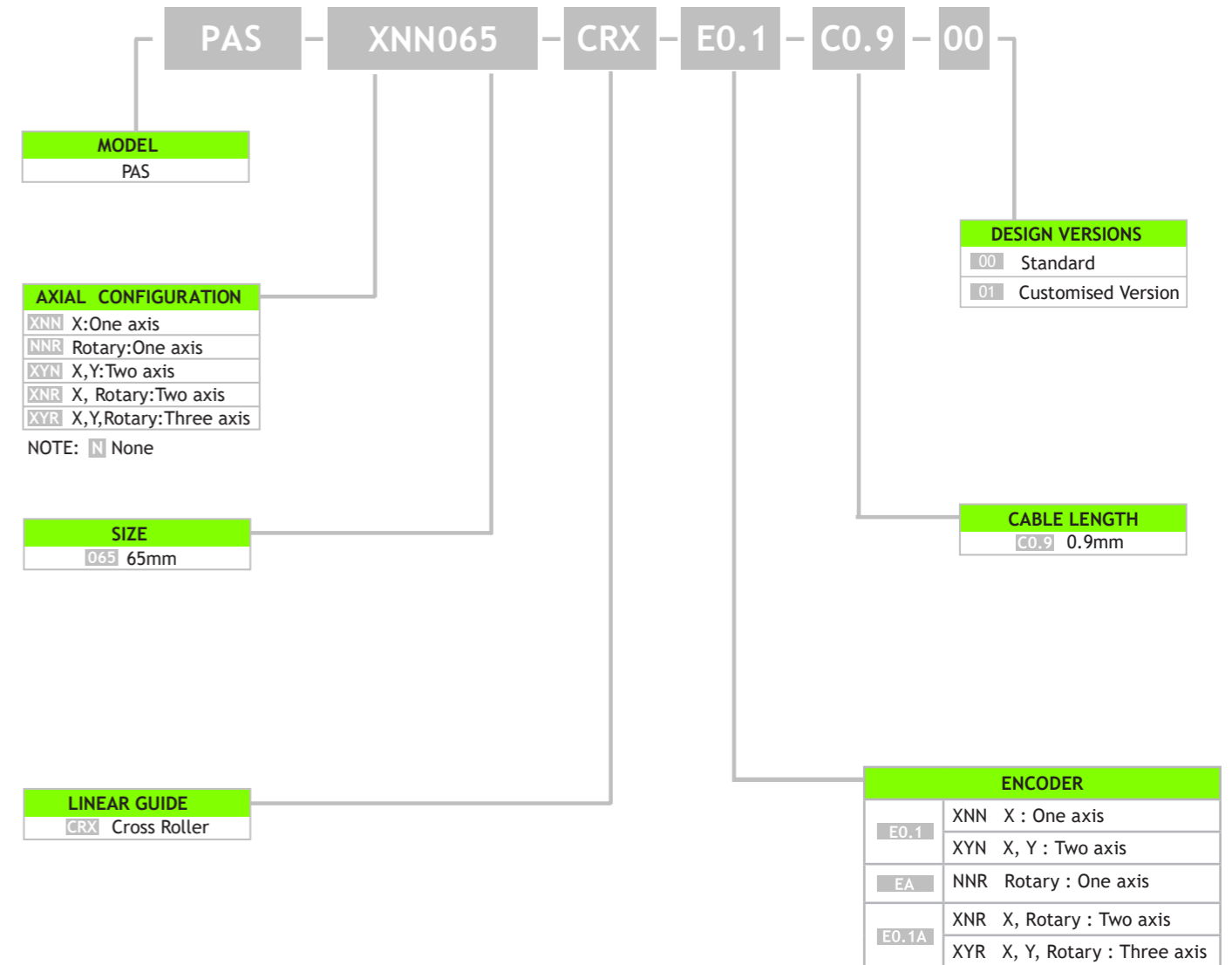
- Direct drive technology
- Compact and low profile
- Cross roller bearing for excellent precision and rigidity
- Zero cogging , zero backlash and zero hysteresis
- Low moving mass, fast response
- Integrated high precision linear encoder
- Excellent reliability
- Stackable configuration

**Technical specifications subject to change without prior notice*

APPLICATION

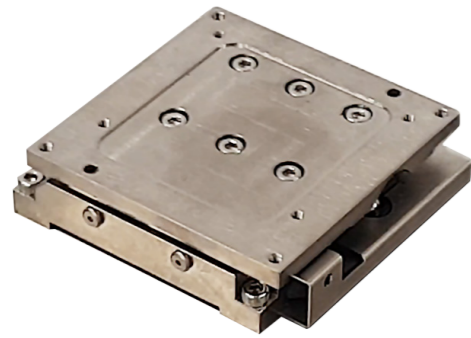
- Alignment process
- Inspection
- Pick and Place
- Dispensing
- Printing
- Laser marking

PART NUMBERING SYSTEM



PAS SERIES

Alignment Stage



PAS SERIES

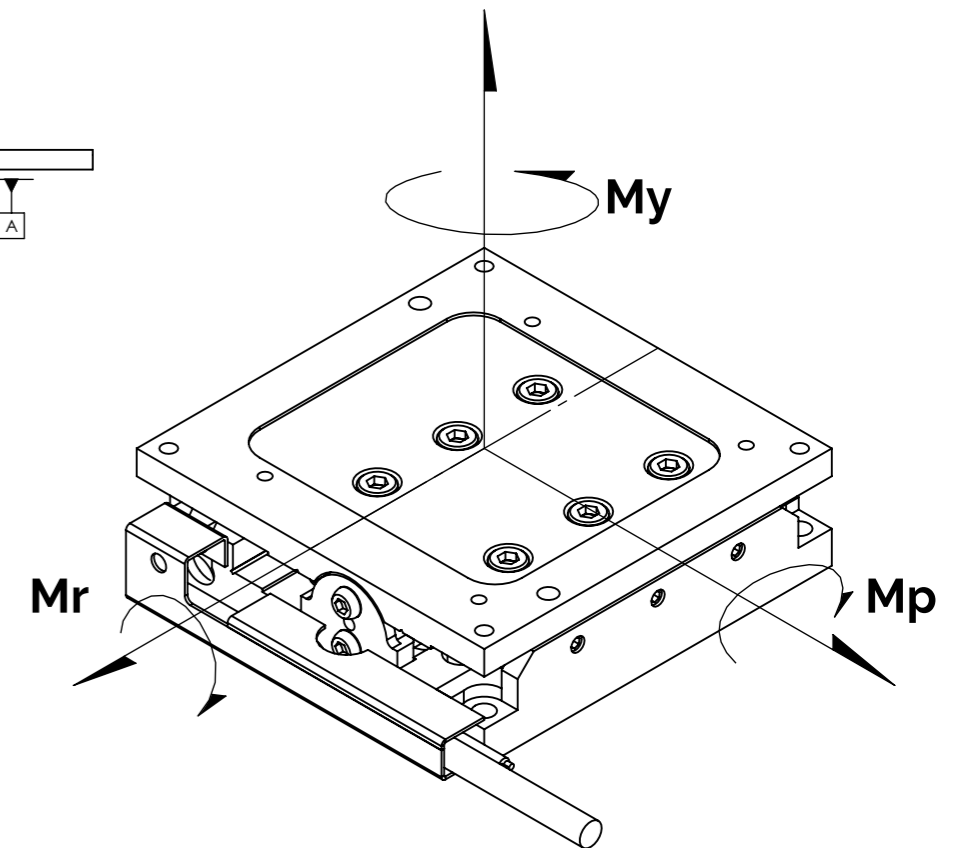
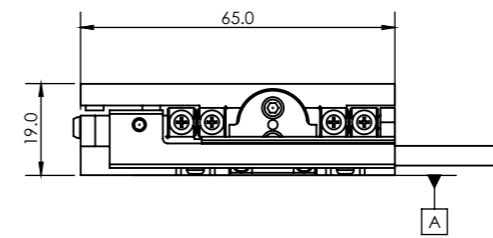
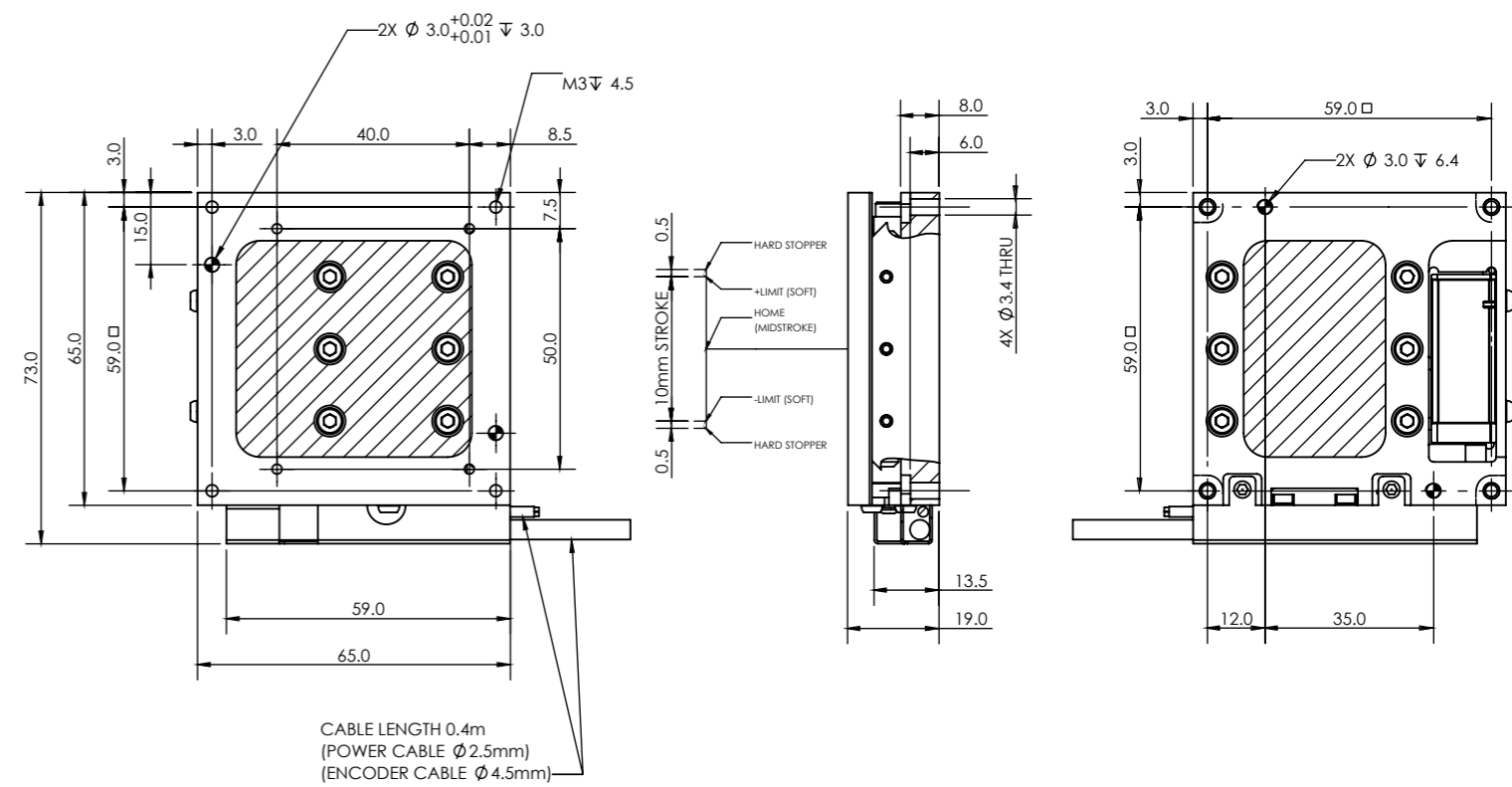
- Direct drive technology
- Compact and low profile
- Low moving mass, fast respon
- Cross roller bearing for excellent precision and rigidity
- Stackable configuration

| SPECIFICATION | | MODEL |
|----------------------------------|-------|-----------------------|
| | | PAS-XNN065-CRX |
| Performance | Unit | |
| Stroke | mm | 10.0 |
| Peak Force | N | 30.1 |
| Continuous Stall Force @ 100°C* | N | 4.3 |
| Peak Power @ 100°C* | W | 254.8 |
| Continuous Power @ 100°C | W | 5.2 |
| Electrical | | |
| Peak Current | A | 7.0 |
| Continuous Stall Current @ 100°C | A | 1.0 |
| Force Constant @ Mid Stroke | N/A | 4.3 |
| Back EMF Constant @ Mid Stroke | V/m/s | 4.3 |
| Coil Resistance @ 25°C | ohm | 4.0 |
| Coil Resistance @ 100°C | ohm | 5.2 |
| Inductance @ 1kHz (Inside fully) | mH | 0.5 |
| Motor Constant @ 100°C | N//W | 1.9 |
| Max. Terminal Voltage | Vdc | 48 |
| Thermal | | |
| Thermal Resistance @ 100°C | °C/W | 14.4 |
| Max. Coil Temperature | °C | 110 |
| Mechanical | | |
| Moving Mass | kg | 0.21 |
| Total Mass | kg | 0.48 |
| Resolution | um | 0.1 |
| Repeatability** | um | ±0.5 |
| Straightness | um | ±2.0 |
| Flatness | um | ±2.0 |
| Type of Linear Bearing | | X-Roller Bearing |
| Surface Treatment | | EN |
| Moment | | |
| M_y | Nm | 2.75 |
| M_R | Nm | 1.44 |
| M_P | Nm | 2.00 |

Notes:

1. *Ambient temperature 25°C, heat dissipation by nation convection, without heat sink attached.
2. Specification tolerance: ±10%
3. ** Depend on encoder resolution.
4. Peak force and current: 4% duty ratio and 1 second duration.
5. PAS-YNN065-CRX specification same as PAS-NXN065-CRX
6. Specifications are subject to change without prior notice.

XNN065-CRX

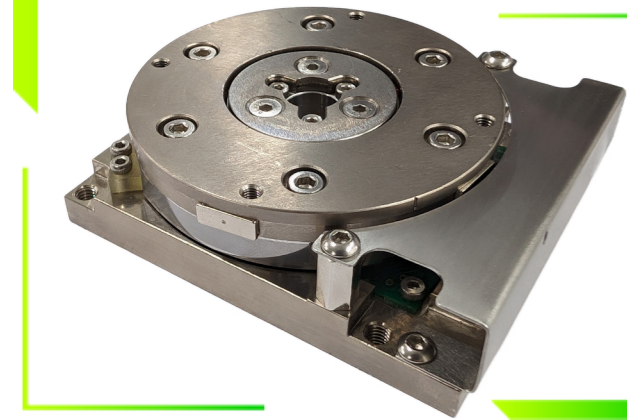


PAS SERIES

Alignment Stage

PAS SERIES

- Direct drive technology
- Compact and low profile
- Low moving mass, fast respon
- Cross roller bearing for excellent precision and rigidity
- Stackable configuration



SPECIFICATION

MODEL

PAS-NNR065-CRX

Performance

Unit

| Performance | Unit | |
|----------------------------|--------|-------|
| Stroke | degree | ±25.0 |
| Peak Torque | N.m | 0.721 |
| Continuous Torque @ 100°C* | N.m | 0.09 |
| Peak Power @ 100°C | W | 692.4 |
| Continuous Power @ 100°C* | W | 10.8 |

Electrical

| | | |
|----------------------------------|-----------|--------|
| Peak Current | Apk | 9.050 |
| Continuous Current @ 100°C | Apk | 1.130 |
| Continuous Stall Current @ 100°C | Arms | 0.800 |
| Torque Constant | N.m/Apk | 0.08 |
| Back EMF Constant L-L | Vpk/rad/s | 0.092 |
| Resistance L-L @ 25°C | ohm | 8.65 |
| Resistance L-L @ 100°C* | ohm | 11.272 |
| Inductance L-L @ 1kHz | mH | 1.480 |
| Motor Constant @ 100°C* | N.m//W | 0.027 |
| Max. Terminal Voltage | Vdc | 48.0 |

Thermal

| | | |
|----------------------------|------|-----|
| Thermal Resistance @ 100°C | °C/W | 6.9 |
| Max. Winding Temperature | °C | 110 |

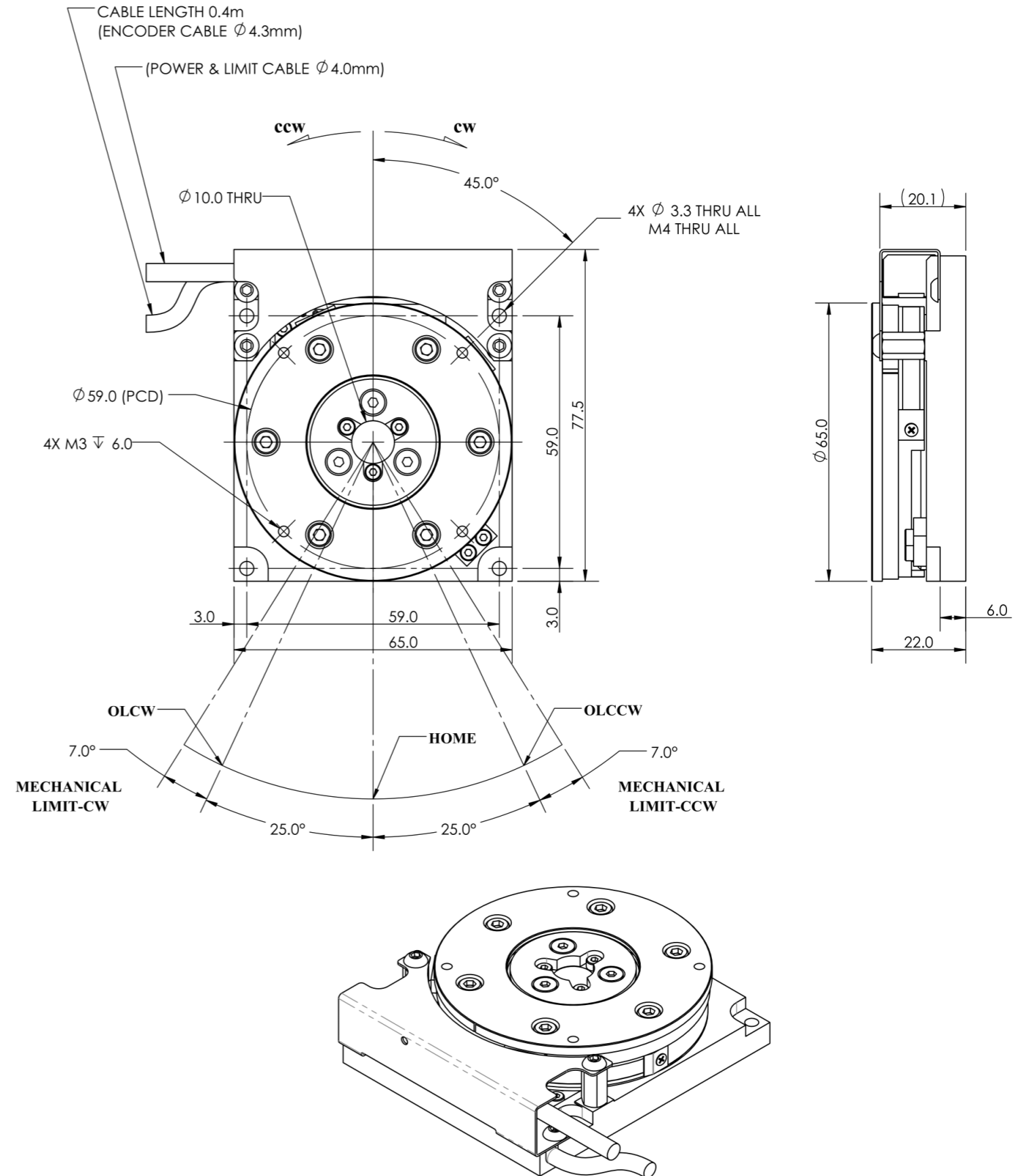
Mechanical

| | | |
|-------------------------------|-------------------|-----------------------|
| Rotor Inertia | kg.m ² | 0.00014 |
| Motor Weight | kg | 0.5 |
| Magnetic Pitch (N-N) | degree | 60 |
| Max. Speed | degree/sec | 720 |
| Max. Axial Load | kg | 2.25 |
| Axial Run-out (no load) | um | ±8.0 |
| Radial Run-out (no load) | um | ±8.0 |
| Resolution (after quadrature) | LPR | A (Analogue) 4,966 |
| Parallelism | um | ±8.0 |
| Repeatability** | arc-sec | ±1.3 |
| Surface Treatment | | EN |

Notes:

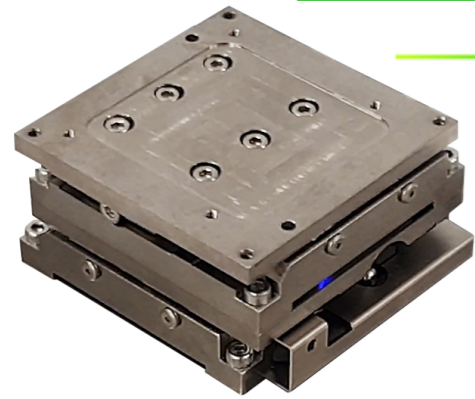
1. Apk=1.414 * Arms; Vpk=1.414 * Vrms
2. *Ambient temperature 25°C, heat dissipation by natural convection, without heat sink attached.
3. Specifications tolerance: ±10%.
4. ** Depend on encoder resolution.
5. Peak force and current: 4% duty ratio and 1 second duration.
6. Specifications are subject to change without prior notice.

NNR065-CRX



PAS SERIES

Alignment Stage



PAS SERIES

- Direct drive technology
- Compact and low profile
- Low moving mass, fast respon
- Cross roller bearing for excellent precision and rigidity
- Stackable configuration

SPECIFICATION

MODEL

PAS-XYN065-CRX

Mechanical Unit

X Stage

| | | |
|------------------------|------|------|
| Stroke | mm | 10.0 |
| Lower Axis Moving Mass | kg | 0.7 |
| X-Resolution | um | 0.1 |
| Peak Force | N | 30 |
| Continuous Force | N | 4.3 |
| Repeatability | um | ±0.5 |
| Straightness | um | ±2.0 |
| Max Speed | mm/s | 691 |

Y Stage

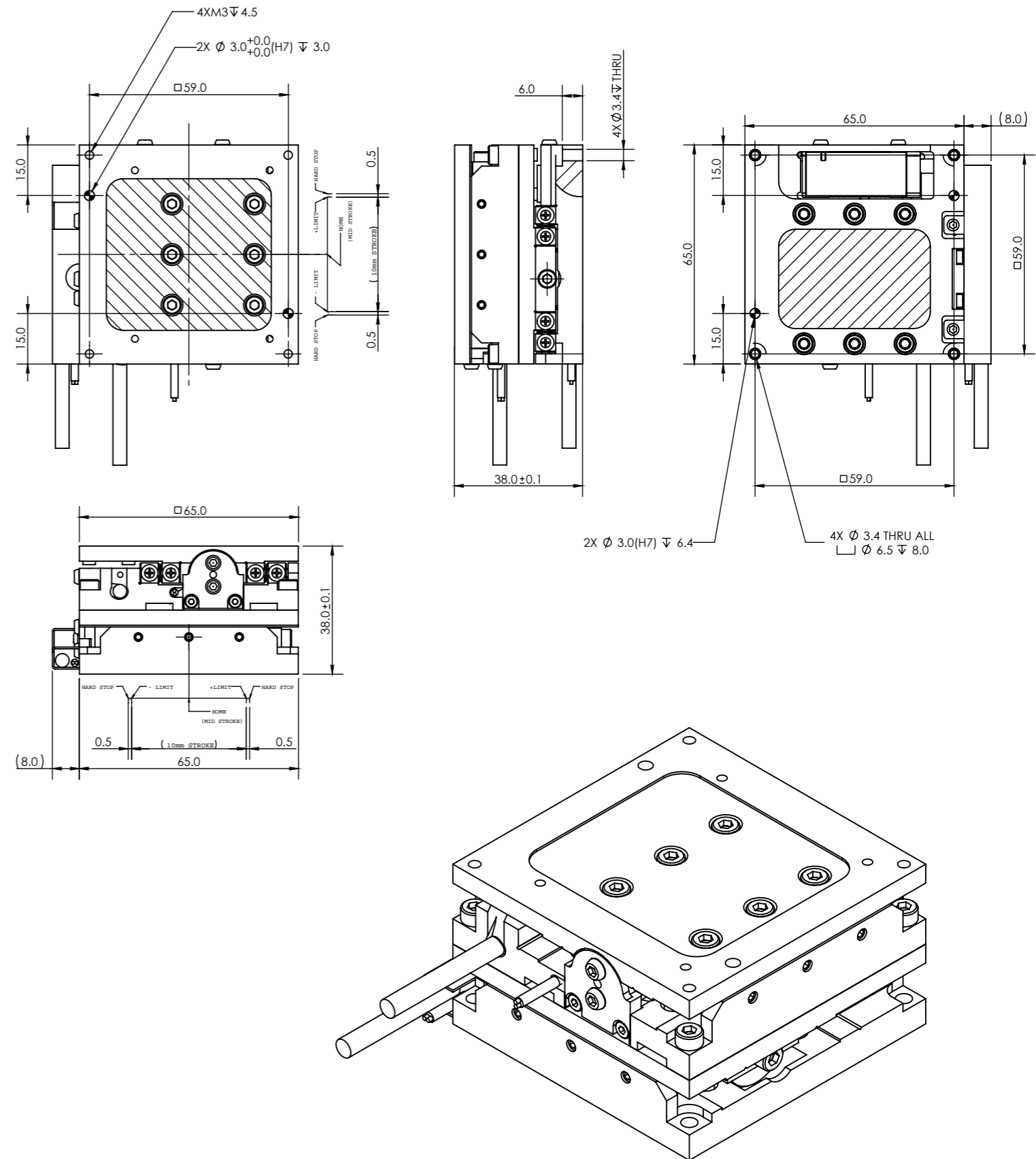
| | | |
|------------------------|------|------|
| Stroke | mm | 10 |
| Lower Axis Moving Mass | kg | 0.21 |
| X-Resolution | um | 0.1 |
| Peak Force | N | 30 |
| Continuous Force | N | 4.3 |
| Repeatability | um | ±0.5 |
| Straightness | um | ±2.0 |
| Max Speed | mm/s | 691 |

PAS-XYN065-CBX

| | | |
|------------------------|-----|------------------|
| Total Mass | kg | 0.98 |
| Resolution | um | 0.1 |
| Max. Axial Load | kg | 1.9 |
| Parallelism | um | ±5.0 |
| Repeatability** | um | ±0.5 |
| Straightness | um | ±2.0 |
| Flatness | um | ±4.0 |
| Type of Linear Bearing | --- | X-Roller Bearing |
| Surface Treatment | --- | EN |

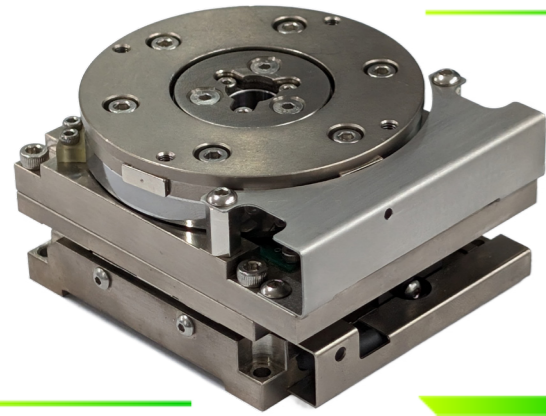
- Notes:
1. Specifications tolerance: ±10%.
 2. ** Depend on encoder resolution.
 3. Peak force and current: 4% duty ratio and 1 second duration.
 4. Specifications are subject to change without prior notice.

XYN065-CRX



PAS SERIES

Alignment Stage



PAS SERIES

- Direct drive technology
- Compact and low profile
- Low moving mass, fast respon
- Cross roller bearing for excellent precision and rigidity
- Stackable configuration

SPECIFICATION

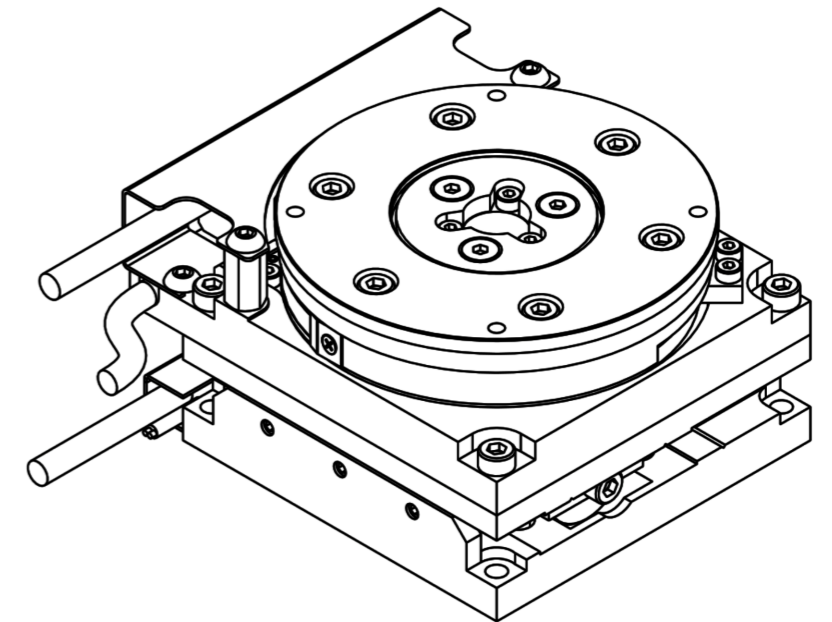
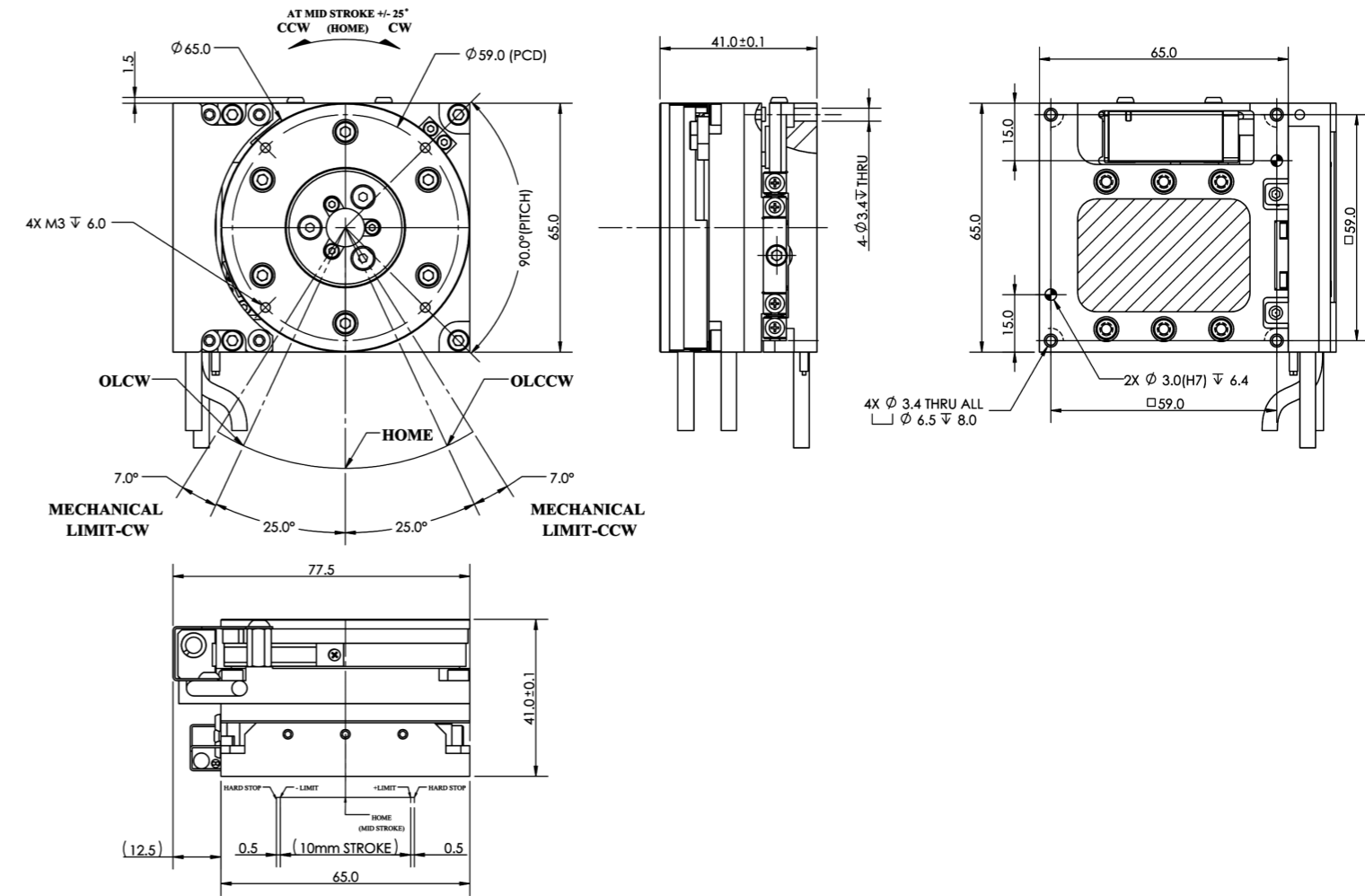
MODEL

PAS-XNR065-CRX

| Mechanical | Unit | |
|-------------------------------|-------------------|------------------|
| R Stage | | |
| Stroke | degree | ±25.0 |
| Rotor Inertia | kg.m ² | 0.00014 |
| Magnatic Pitch (N-N) | degree | 60 |
| Max. Speed | degree/sec | 720 |
| Max. Axial Load | kg | 2.25 |
| Axial Run-out (no load) | um | ±8.0 |
| Radial Run-out (no load) | um | ±8.0 |
| A (Analogue) | | |
| Resolution (after quadrature) | LPR | 4,966 |
| Repeatability | arc-sec | ±1.3 |
| X Stage | | |
| Stroke | mm | 10.0 |
| Upper Axis Moving Mass | kg | 0.71 |
| Resolution | um | 0.1 |
| Repeatability | um | ±0.5 |
| Straightness | um | ±2.0 |
| Type of Linear Bearing | | X-Roller Bearing |
| Surface Treatment | | EN |
| PAS-XNR065-CRX | | |
| Total Mass | kg | 0.98 |
| Flatness | um | ±2.0 |

- Notes:
1. Specifications tolerance: ±10%.
 2. ** Depend on encoder resolution.
 3. Peak force and current: 4% duty ratio and 1 second duration.
 4. Specifications are subject to change without prior notice.

XNR065-CRX

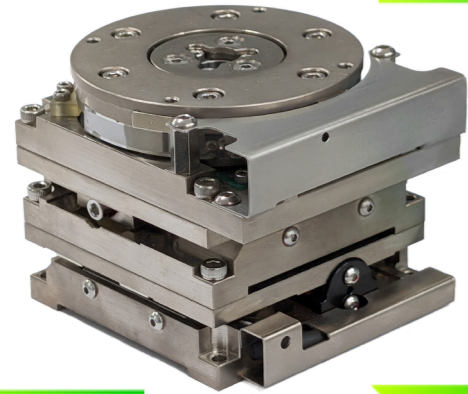


PAS SERIES

Alignment Stage

PAS SERIES

- Direct drive technology
- Compact and low profile
- Low moving mass, fast respon
- Cross roller bearing for excellent precision and rigidity
- Stackable configuration



SPECIFICATION

MODEL

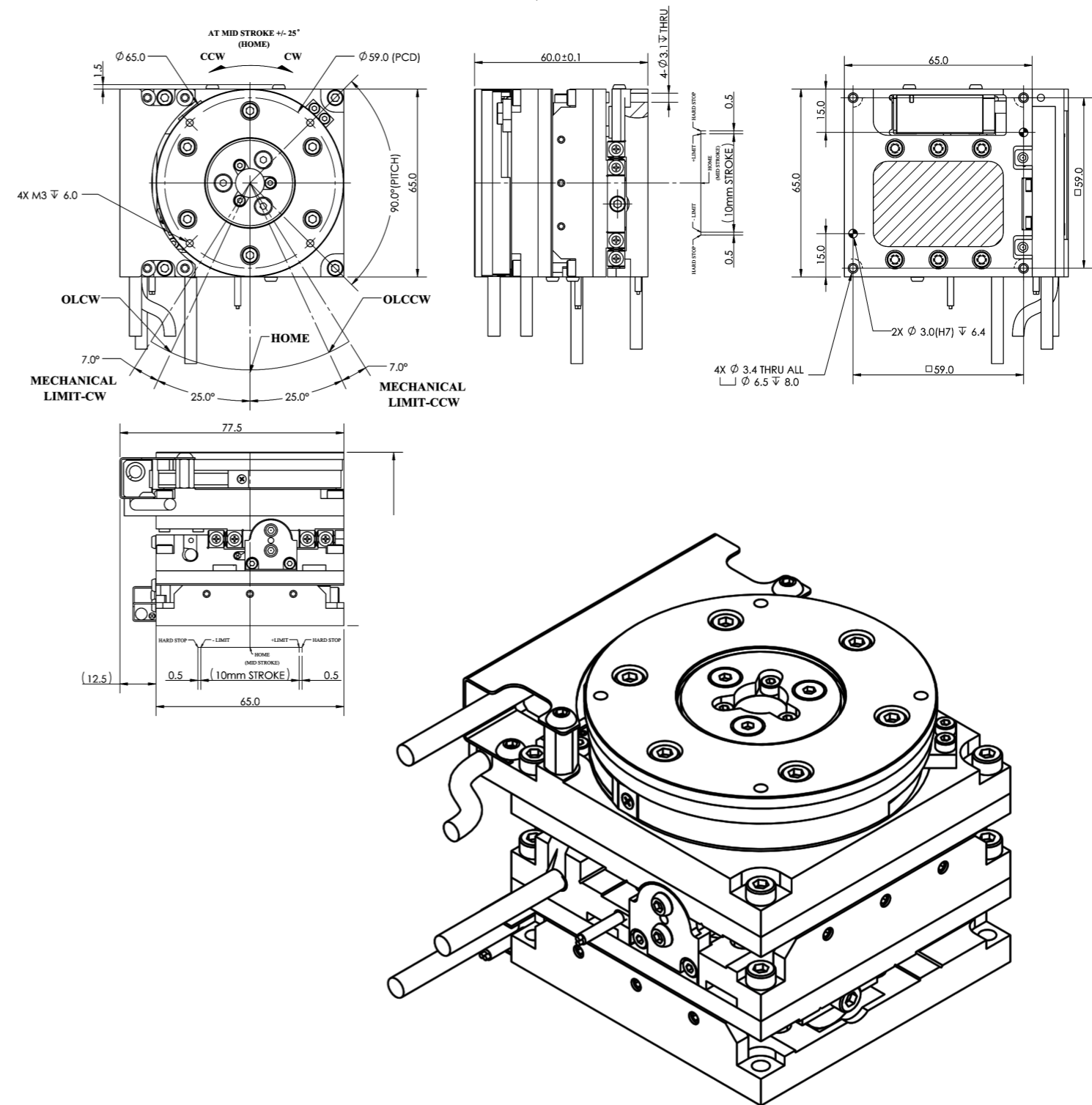
PAS-XYR065-CRX

Mechanical Unit

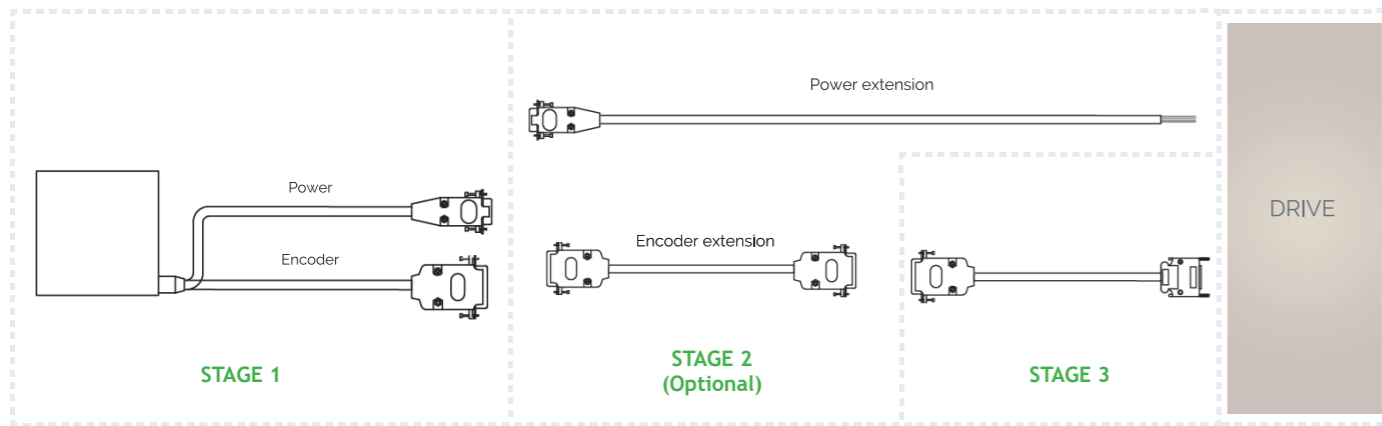
| | | R Stage |
|-------------------------------|-------------------|-----------------------|
| Stroke | degree | ±25.0 |
| Rotor Inertia | kg.m ² | 0.00014 |
| Magnatic Pitch (N-N) | degree | 60 |
| Max. Speed | degree/sec | 720 |
| Max. Axial Load | kg | 2.25 |
| Axial Run-out (no load) | um | ±8.0 |
| Radial Run-out (no load) | um | ±8.0 |
| Resolution (after quadrature) | LPR | A (Analogue) 4,966 |
| Repeatability | arc-sec | ±1.3 |
| | | X Stage |
| Stroke | mm | 10.0 |
| Bottom Axis Moving Mass | kg | 0.71 |
| Resolution | um | 0.1 |
| Repeatability | um | ±0.5 |
| Straightness | um | ±2.0 |
| Type of Linear Bearing | | X-Roller Bearing |
| Surface Treatment | | EN |
| | | Y Stage |
| Stroke | mm | 10.0 |
| Upper Axis Moving Mass | kg | 1.19 |
| Resolution | um | 0.1 |
| Repeatability | um | ±0.5 |
| Straightness | um | ±2.0 |
| Type of Linear Bearing | | X-Roller Bearing |
| Surface Treatment | | EN |
| | | PAS-XYR065-CRX |
| Total Mass | kg | 1.47 |
| Flatness | um | ±2.0 |

- Notes:
1. Specifications tolerance: ±10%.
 2. ** Depend on encoder resolution.
 3. Peak force and current: 4% duty ratio and 1 second duration.
 4. Specifications are subject to change without prior notice.

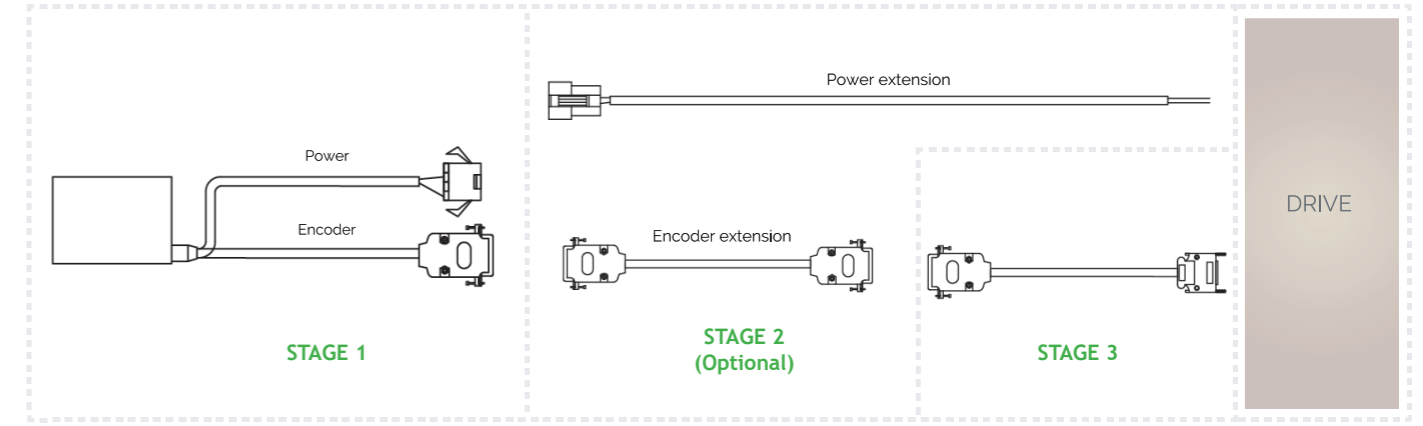
XYR065-CRX



CABLE OPTION - ROTARY



CABLE OPTION - LINEAR



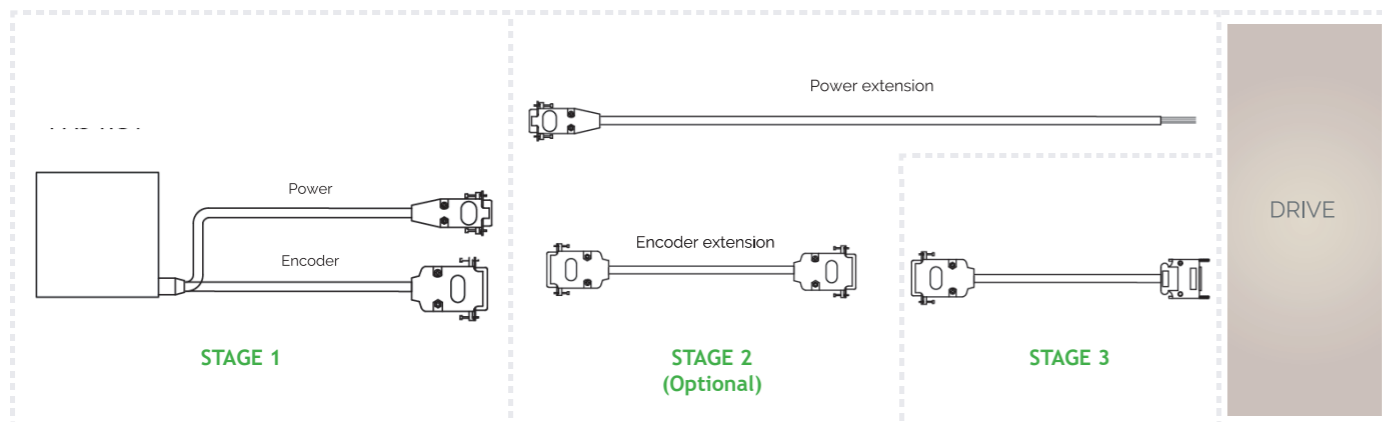
STAGE 1 | PAS SERIES CABLE COLOUR CODE AND PIN OUT

| MOTOR POWER CABLE/LIMIT SENSOR | | ENCODER CONNECTOR | | | | | | | | | | | | | | | | | | | | | |
|--------------------------------|-----|--|---|------|------|-----|------|-----|----|-----|-----|----|------|--------|-----|----|----|----|-----|------|----|----|----|
| 9NF | | | <table border="1"> <tr> <th>PIN</th> <th>CODE</th> <th>PIN</th> <th>CODE</th> </tr> <tr> <td>1</td> <td>M1</td> <td>9</td> <td>V1+</td> </tr> <tr> <td>2</td> <td>M2</td> <td>10</td> <td>V2+</td> </tr> <tr> <td>3</td> <td>M3</td> <td>11</td> <td>V0-</td> </tr> <tr> <td>CASE</td> <td>PE</td> <td>12</td> <td>0V</td> </tr> </table> | PIN | CODE | PIN | CODE | 1 | M1 | 9 | V1+ | 2 | M2 | 10 | V2+ | 3 | M3 | 11 | V0- | CASE | PE | 12 | 0V |
| | PIN | CODE | PIN | CODE | | | | | | | | | | | | | | | | | | | |
| | 1 | M1 | 9 | V1+ | | | | | | | | | | | | | | | | | | | |
| | 2 | M2 | 10 | V2+ | | | | | | | | | | | | | | | | | | | |
| | 3 | M3 | 11 | V0- | | | | | | | | | | | | | | | | | | | |
| CASE | PE | 12 | 0V | | | | | | | | | | | | | | | | | | | | |
| | | <table border="1"> <tr> <td>4</td> <td>+5V</td> <td>13</td> <td>0V</td> </tr> <tr> <td>5</td> <td>+5V</td> <td>14</td> <td>CAL</td> </tr> <tr> <td>6</td> <td>E-</td> <td>CASE</td> <td>SHIELD</td> </tr> <tr> <td>7</td> <td>Vp</td> <td></td> <td></td> </tr> <tr> <td>8</td> <td>Vq</td> <td></td> <td></td> </tr> </table> | 4 | +5V | 13 | 0V | 5 | +5V | 14 | CAL | 6 | E- | CASE | SHIELD | 7 | Vp | | | 8 | Vq | | | |
| 4 | +5V | 13 | 0V | | | | | | | | | | | | | | | | | | | | |
| 5 | +5V | 14 | CAL | | | | | | | | | | | | | | | | | | | | |
| 6 | E- | CASE | SHIELD | | | | | | | | | | | | | | | | | | | | |
| 7 | Vp | | | | | | | | | | | | | | | | | | | | | | |
| 8 | Vq | | | | | | | | | | | | | | | | | | | | | | |

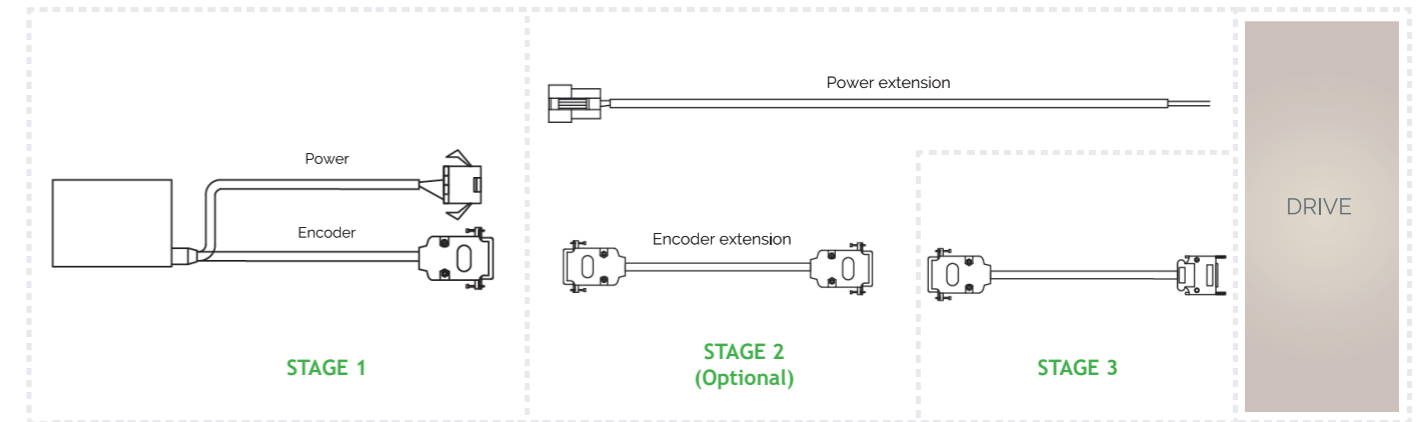
STAGE 1 | PAS SERIES CABLE COLOUR CODE AND PIN OUT

| MOTOR POWER CABLE/LIMIT SENSOR | | ENCODER CONNECTOR | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
|--------------------------------|--------|---|--|------|------|-----|------|----|---------|-----|-----|-----|------|--------|-----|-----|-----------|----|-----|----|---|----|-----|---|--|--|-----|---|--|--|-----|----|--|--|-----|----|--|--|-----|----|--|--|-----|---|--|--|------|--------|--|--|
| 9NF | | | <table border="1"> <tr> <th>PIN</th> <th>CODE</th> <th>PIN</th> <th>CODE</th> </tr> <tr> <td>P1</td> <td>RED (+)</td> <td>9</td> <td>V1+</td> </tr> <tr> <td>P2</td> <td>-</td> <td>10</td> <td>V2+</td> </tr> <tr> <td>P3</td> <td>BLACK (-)</td> <td>11</td> <td>V0-</td> </tr> <tr> <td>P4</td> <td>-</td> <td>12</td> <td>0V</td> </tr> </table> | PIN | CODE | PIN | CODE | P1 | RED (+) | 9 | V1+ | P2 | - | 10 | V2+ | P3 | BLACK (-) | 11 | V0- | P4 | - | 12 | 0V | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| | PIN | CODE | PIN | CODE | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| | P1 | RED (+) | 9 | V1+ | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| | P2 | - | 10 | V2+ | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| | P3 | BLACK (-) | 11 | V0- | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| P4 | - | 12 | 0V | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| | | <table border="1"> <tr> <td>P5</td> <td>B-</td> <td>13</td> <td>0V</td> </tr> <tr> <td>P6</td> <td>A-</td> <td>14</td> <td>CAL</td> </tr> <tr> <td>P7</td> <td>+5V</td> <td>CASE</td> <td>SHIELD</td> </tr> <tr> <td>P8</td> <td>+5V</td> <td></td> <td></td> </tr> <tr> <td>P9</td> <td>0V</td> <td></td> <td></td> </tr> <tr> <td>P10</td> <td>Q</td> <td></td> <td></td> </tr> <tr> <td>P11</td> <td>P</td> <td></td> <td></td> </tr> <tr> <td>P12</td> <td>Z+</td> <td></td> <td></td> </tr> <tr> <td>P13</td> <td>B+</td> <td></td> <td></td> </tr> <tr> <td>P14</td> <td>A+</td> <td></td> <td></td> </tr> <tr> <td>P15</td> <td>-</td> <td></td> <td></td> </tr> <tr> <td>CASE</td> <td>SHIELD</td> <td></td> <td></td> </tr> </table> | P5 | B- | 13 | 0V | P6 | A- | 14 | CAL | P7 | +5V | CASE | SHIELD | P8 | +5V | | | P9 | 0V | | | P10 | Q | | | P11 | P | | | P12 | Z+ | | | P13 | B+ | | | P14 | A+ | | | P15 | - | | | CASE | SHIELD | | |
| P5 | B- | 13 | 0V | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| P6 | A- | 14 | CAL | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| P7 | +5V | CASE | SHIELD | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| P8 | +5V | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| P9 | 0V | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| P10 | Q | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| P11 | P | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| P12 | Z+ | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| P13 | B+ | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| P14 | A+ | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| P15 | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| CASE | SHIELD | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |

STAGE 2 | PAS SERIES EXTENSION CABLE



STAGE 2 | PAS SERIES EXTENSION CABLE



| Extension Cable | | Part Number |
|-------------------------|--|-----------------------|
| Power Extension Cable | | CBL_EXT_PWR0_X.X |
| Encoder Extension Cable | | CBL_EXT_REN00A_UL_X.X |

| Extension Cable | | Part Number |
|-------------------------|--|---------------------|
| Power Extension Cable | | CBL_EXT_PWR_CVC_X.X |
| Encoder Extension Cable | | CBL_EXT_REN00_X.X |

| | |
|----------------|------------------|
| Customer Name: | Date (DD/MM/YY): |
| Contact Email: | |

PBA LINEAR MOTOR SELECTION QUESTIONNAIRE

1. Application Description

| |
|--|
| |
| |
| |
| |
| |

1a. Application Sketch With Approx Dimensions

2. Load Parameter

| | | |
|----------------------------------|-----|----|
| Moving mass (without motor coil) | kg | |
| Frictional force | N | |
| Opposing force | N | |
| Mx | N.m | My |
| | N.m | Mz |
| | N.m | |

Stage Requirements

| | |
|-------------------------------------|--------------------------------------|
| <input type="checkbox"/> Horizontal | <input type="checkbox"/> Vertical |
| <input type="checkbox"/> Sidewall | <input type="checkbox"/> Upside-down |

3. Motion Parameter

| | Profile 1 | Profile 2 | Profile 3 |
|-----------------|------------------|-----------|-----------|
| Moving distance | mm | | |
| Moving time | s | | |
| Moving velocity | m/s | | |
| Acceleration | m/s ² | | |
| Dwell time | s | | |

4. Command/Bus (Please Circle Accordingly)

Pulse and direction / Analog / EtherCAT / IO trigger / Other : _____

5. Encoder (Please Circle Accordingly)

| | |
|---------------------------------|----|
| Resolution | um |
| Incremental / Absolute / Analog | |

6. Motion Precision

| | |
|---------------|-------|
| Accuracy | um/mm |
| Repeatability | um |

7. Mechanical Specification

| | |
|---------------------------------|-------|
| Effective stroke | mm |
| Flatness | um/mm |
| Straightness | um/mm |
| Space constraints (L x W x H) | mm |

8. Working Environment

| | |
|------------------|----|
| Room temperature | °C |
| Clean room class | |

9. Additional Requirements (Please Tick () Accordingly)

| | | | | |
|--------------------|------------|-----------|---------|--------------|
| Motor cable length | Controller | Amplifier | Encoder | Other: _____ |
| m | | | | |

10. Actuator



11. Remarks: If you have any special motion request for sizing procedure, please specify your requirement in below remarks.

| |
|--|
| |
| |
| |

PBA Systems is a one-stop robotics provider with a focus on the development of core technology to offer a robust range of products and solutions in precision robotics and general robotics - enabling companies to thrive by making Industry 4.0 technology accessible to the market.

Our core strength is in design, development, and manufacturing of direct drive motor design and manufacturing, motion control, and precision modular assemblies.

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PBA SYSTEMS LINEAR MOTOR SIZER SOFTWARE

PBA Systems Motor Sizer Software is available to download from our website to assist in the calculation and selection.

Kindly visit us at www.pbasystems.com.sg or simply scan the QR CODE

SIMULATED PERFORMANCE CHARTS

Motor Sizer

Project Details: Customer Name: PBA Customer, Project Name: Project1, Date: 2023/12/5

Axis Details: Axis Name: New Axis, Motor Category: PLA_PIX, Safety Margin: 100, Actuator, Max Distance: 1000 mm

| No | Motion Profile | Travel Distance (m) | Travel Time (s) | Max. Speed (m/s) | Max. Accel. (m/s ²) | Dwell Time (s) | Mass of Load (kg) | Angle Of Incl. (°) | Direction | Coefficient of Friction | Opposing Force (N) | Ambient Temp. (°C) | RMS Force (N) | Peak Force (N) | Frictional Force (N) | Accel. Time (s) | Cruise Time (s) | Decel. Time (s) | Total Time (s) |
|----|----------------|---------------------|-----------------|------------------|---------------------------------|----------------|-------------------|--------------------|-----------|-------------------------|--------------------|--------------------|---------------|----------------|----------------------|-----------------|-----------------|-----------------|----------------|
| 1 | Custom | 1.000 | 0.750 | 2.000 | 8.000 | 0.000 | 5.000 | 0.000 | | 0.003 | 0.000 | 30.000 | 32.660 | 40.147 | 0.147 | 0.250 | 0.250 | 0.250 | 0.000 |

Final Calculations for Axis

| | |
|-----------------------|------------------------|
| Required RMS Force | 32.660 N |
| Required Peak Force | 40.147 N |
| Total Travel Distance | 1.000 m |
| Total Cycle Time | 0.750 s |
| Total Dwell Time | 0.000 s |
| Max Speed | 2.000 m/s |
| Max Acceleration | 8.000 m/s ² |
| Max. Ambient Temp. | 30.000 °C |

Recommended Motor

| Motor | Safety (%) |
|-----------------------|------------|
| PLA140-PIX150B-050-C3 | 121 |
| PLA140-PIX150B-050-C4 | 175 |
| PLA180-PIX150B-075-C2 | 149 |
| PLA180-PIX150B-075-C3 | 245 |
| PLA220-PIX150B-100-C2 | 216 |
| PLA140-PIX250B-050-C1 | 108 |

Selected Motor

| | |
|----------------------|-----------------------|
| Motor | PLA140-PIX150B-050-C3 |
| Continuous Force | 104.00 N |
| Peak Force | 363.00 N |
| Continuous Current | 3.30 A |
| Peak Current | 12.70 A |
| Motor Constant | 12.40 N/V |
| Force Constant | 32.00 N/A |
| Back EMF Constant | 36.90 V/(m/s) |
| L To L Resistance | 6.80 ohm |
| L To L Inductance | 16.50 mH |
| Continuous Power | 71.00 W |
| Peak Power | 1081.00 W |
| Carriage Moving Mass | 2.300 kg |
| Coil Length | 142.00 mm |
| Attraction Force | 630.00 N |

Calculated Motor Values for Application

| | | | |
|-------------------|----------------|------------------|---------|
| Reqd. RMS Force | 47.73 N | Reqd. Peak Force | 60.50 N |
| Cont. Current | 1.49 A | Peak Current | 1.89 A |
| Coil Temp | 42.62 °C | DC Bus Voltage | 86.66 V |
| S.F. Current | 121.25 % | L.F. Current | 45.20 % |
| S.F. Force | 117.89 % | L.F. Force | 45.89 % |
| Servo Drive Model | MT-6/25-230AP1 | | |
| Cont. Current | 6.30 A | Peak Current | 25.40 A |

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